



Generative Adversarial Networks to infer velocity component in rotating turbulent flows

T. Li^a, M. Buzzicotti^a, L. Biferale^a and F. Bonaccorso^a

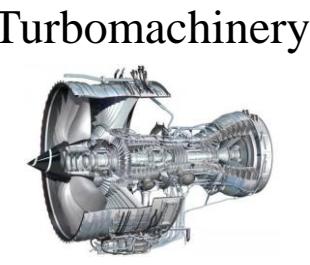
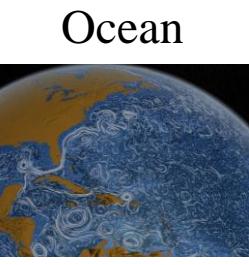
^aDepartment of Physics and INFN, University of Rome “Tor Vergata”, Via della Ricerca Scientifica 1, 00133, Rome, Italy



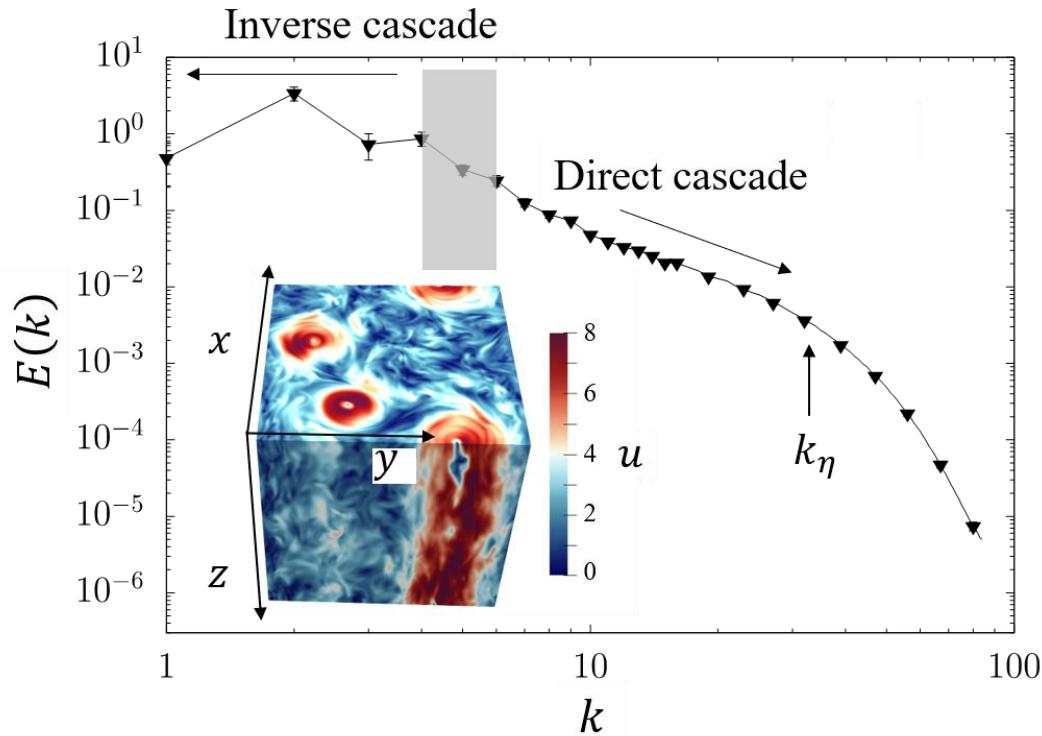
T. Li *et al.*, arXiv:2210.11921 (2022) (accepted by J. Fluid Mech.).

T. Li *et al.*, Eur. Phys. J. E 46, 31 (2023).

Background



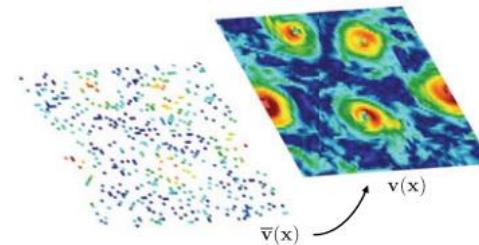
Rotating turbulence



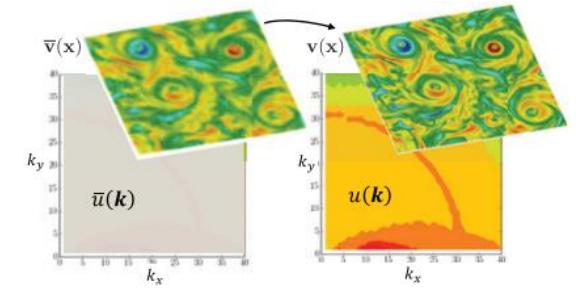
Large-scale vortical structures
Small-scale non-Gaussian fluctuations

Data reconstruction

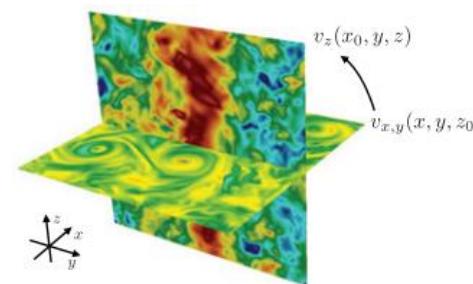
(i) Inpainting



(ii) Super-resolution



(iii) Inference

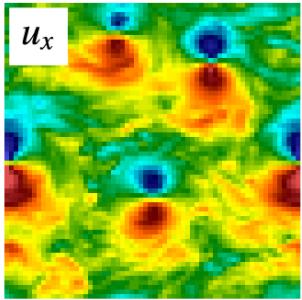


M. Buzzicotti, *Data reconstruction for complex flows using AI: recent progress, obstacles, and perspectives*. Europhysics Letters (2023).

Problem set-up

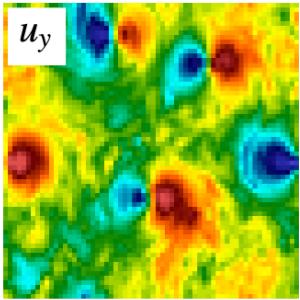
Measurements

(I) in-plane

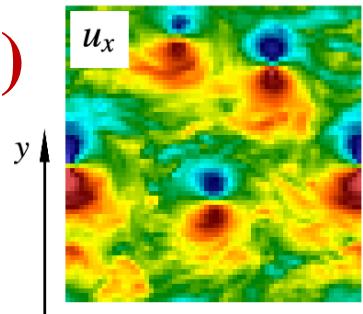


Unknowns

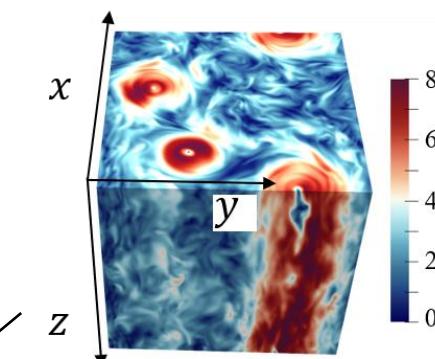
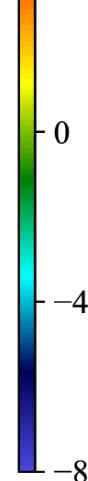
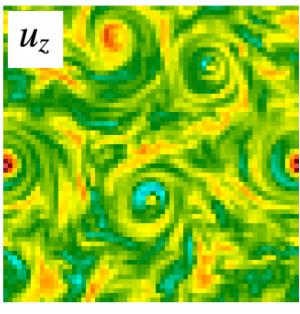
in-plane



(II) in-plane

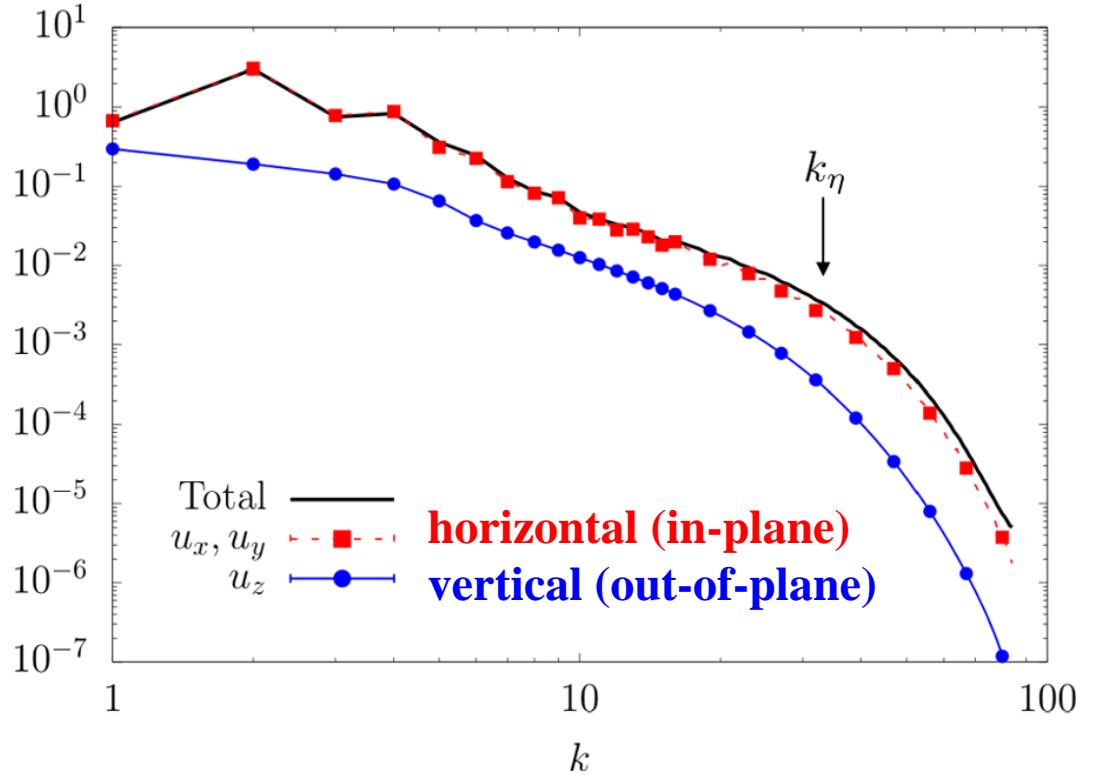


out-of-plane



$z = z_0$

$E(k)$



EPOD inference (*Extended Proper Orthogonal Decomposition*)

$$\mathcal{R}_S(x, y) = \langle \mathbf{u}_S(x) \mathbf{u}_S(y)^T \rangle$$

$$\int_{\Omega} \mathcal{R}_S(x, y) \cdot \boldsymbol{\phi}_S^{(n)}(y) dy = \sigma_n \boldsymbol{\phi}_S^{(n)}(x)$$

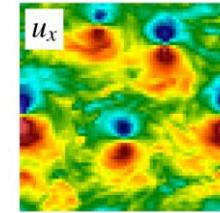
$$\mathbf{u}_S(x) = \sum_{n=1}^{N_{\Omega}} b_S^{(n)} \boldsymbol{\phi}_S^{(n)}(x)$$

$$\boldsymbol{\phi}_S^{(n)}(x) = \langle b_S^{(n)} \mathbf{u}_S(x) \rangle / \sigma_n$$

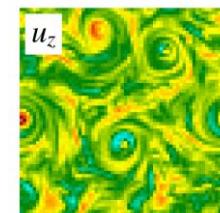
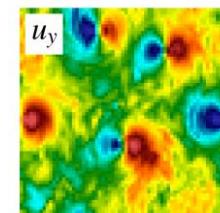
$$\boldsymbol{\phi}_E^{(n)}(x) = \langle b_S^{(n)} \mathbf{u}_G(x) \rangle / \sigma_n \quad (\text{TRAINING})$$



Measured quantities: \mathbf{u}_S



Quantities
to be inferred: \mathbf{u}_G



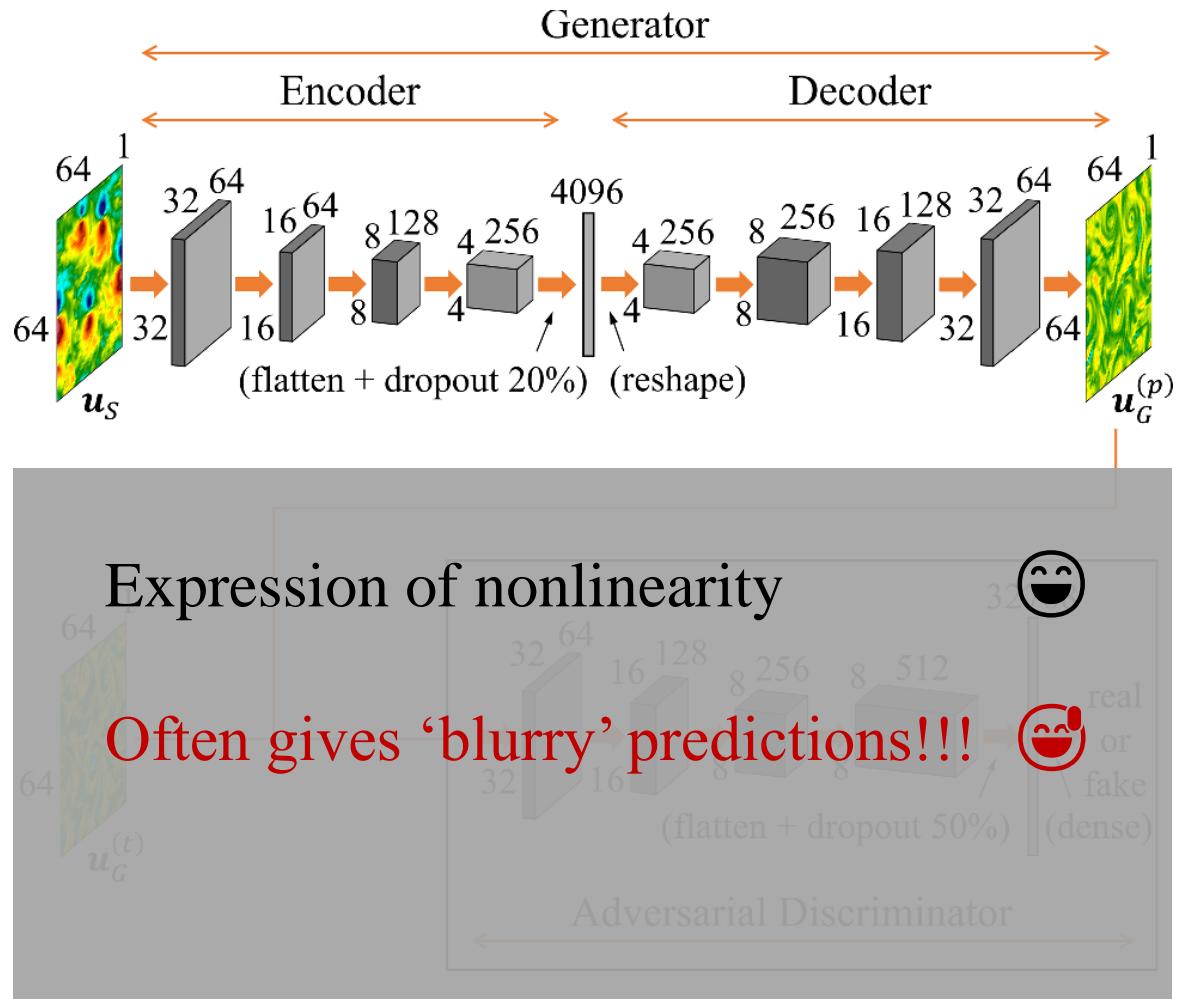
Ω

$$\mathbf{u}_G^{(p)}(x) = \sum_{n=1}^{N_{\Omega}} b_S^{(n)} \boldsymbol{\phi}_E^{(n)}(x) \quad (\text{PREDICTION})$$

$$\text{JSD}(P\|Q) = \frac{1}{2} \text{KL}(P\|M) + \frac{1}{2} \text{KL}(Q\|M), M = \frac{1}{2}(P+Q)$$

$$\text{KL}(P\|Q) = \int_{-\infty}^{\infty} P(x) \log(P(x)/Q(x)) dx$$

CNN-based inference with context encoders



Loss functions

$$\mathcal{L}_{GEN} = (1 - \lambda_{adv})\mathcal{L}_{MSE} + \lambda_{adv}\mathcal{L}_{adv}$$

$$\mathcal{L}_{MSE} = \left\langle \frac{1}{A_\Omega} \int_\Omega \| \mathbf{u}_G^{(p)}(\mathbf{x}) - \mathbf{u}_G^{(t)}(\mathbf{x}) \|^2 d\mathbf{x} \right\rangle$$

$$\mathcal{L}_{adv} = \langle \log(1 - D(\mathbf{u}_G^{(p)})) \rangle$$

↑

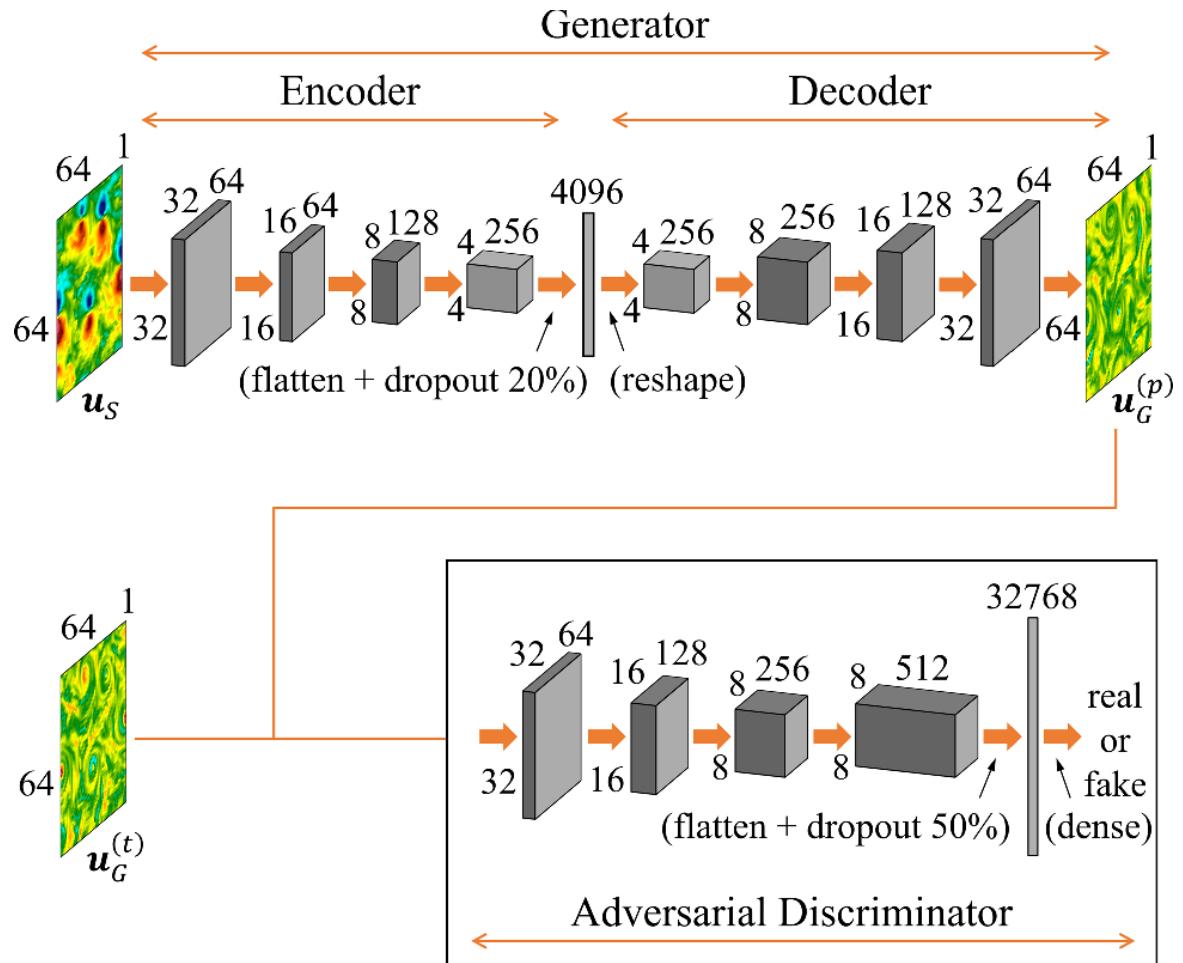
Minimize $\text{JSD}(p_t(u_G) \| p_p(u_G))$

$$\mathcal{L}_{DIS} = \langle \log(D(\mathbf{u}_G^{(t)})) \rangle + \langle \log(1 - D(\mathbf{u}_G^{(p)})) \rangle$$

$$\text{JSD}(P\|Q) = \frac{1}{2} \text{KL}(P\|M) + \frac{1}{2} \text{KL}(Q\|M), M = \frac{1}{2}(P + Q)$$

$$\text{KL}(P\|Q) = \int_{-\infty}^{\infty} P(x) \log(P(x)/Q(x)) dx$$

GAN-based inference with context encoders



Loss functions

$$\mathcal{L}_{GEN} = (1 - \lambda_{adv})\mathcal{L}_{MSE} + \lambda_{adv}\mathcal{L}_{adv}$$

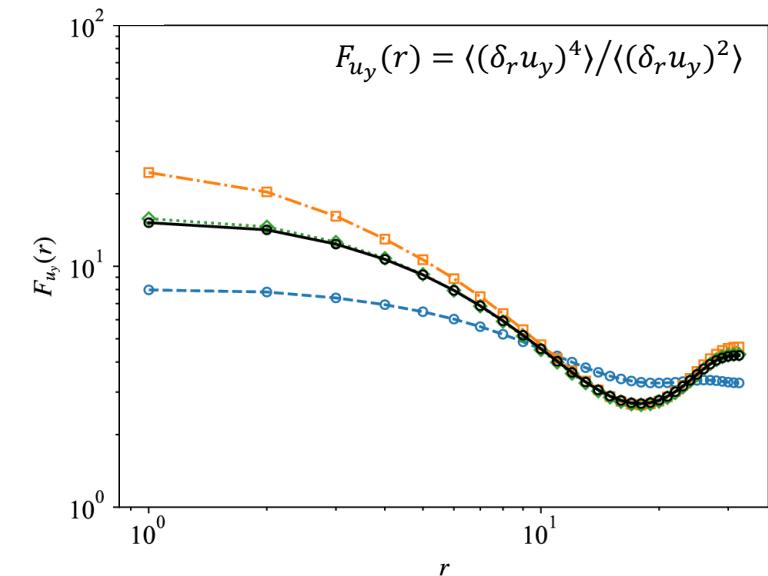
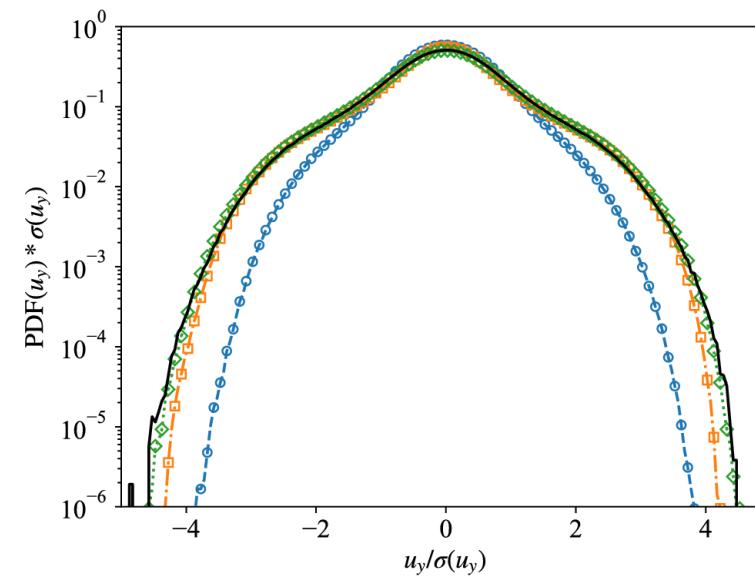
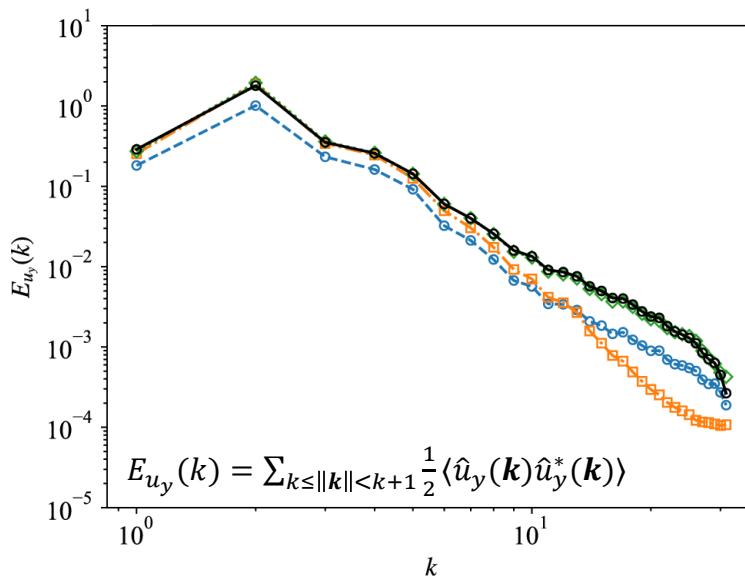
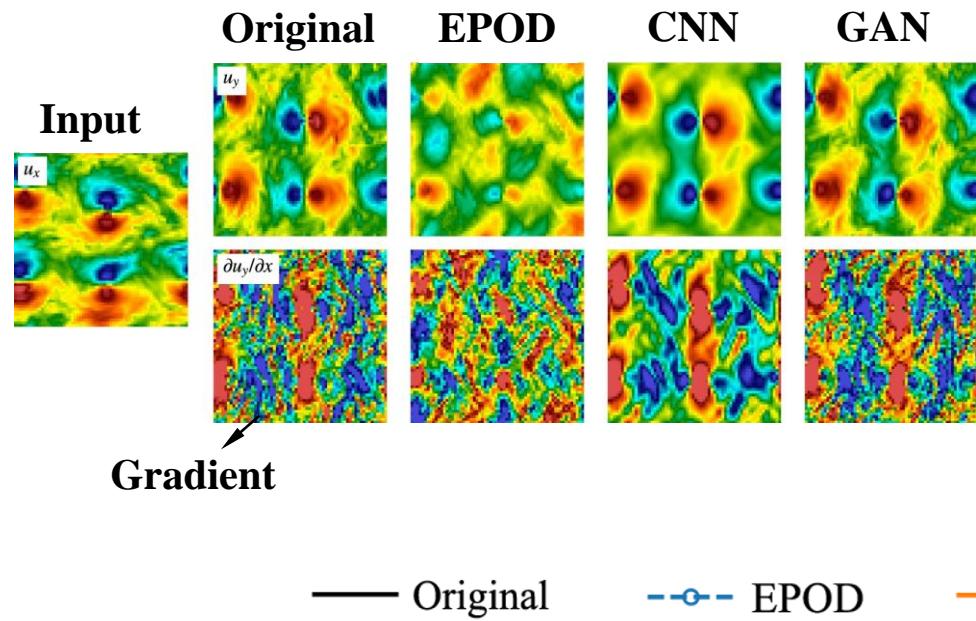
$$\mathcal{L}_{MSE} = \left\langle \frac{1}{A_\Omega} \int_\Omega \| \mathbf{u}_G^{(p)}(\mathbf{x}) - \mathbf{u}_G^{(t)}(\mathbf{x}) \|^2 d\mathbf{x} \right\rangle$$

$$\mathcal{L}_{adv} = \langle \log(1 - D(\mathbf{u}_G^{(p)})) \rangle$$

Minimize $\text{JSD}(p_t(\mathbf{u}_G) \parallel p_p(\mathbf{u}_G))$

$$\mathcal{L}_{DIS} = \langle \log(D(\mathbf{u}_G^{(t)})) \rangle + \langle \log(1 - D(\mathbf{u}_G^{(p)})) \rangle$$

Results: Inference task (I)



Point-wise MSE

$$\rightarrow \text{MSE}(\boldsymbol{u}_G) = \langle \Delta_{\boldsymbol{u}_G} \rangle / E_{\boldsymbol{u}_G}$$

$$\Delta_{\mathbf{u}_G} = \frac{1}{A_\Omega} \int_{\Omega} \| \mathbf{u}_G^{(p)}(\mathbf{x}) - \mathbf{u}_G^{(t)}(\mathbf{x}) \|^2 d\mathbf{x}$$

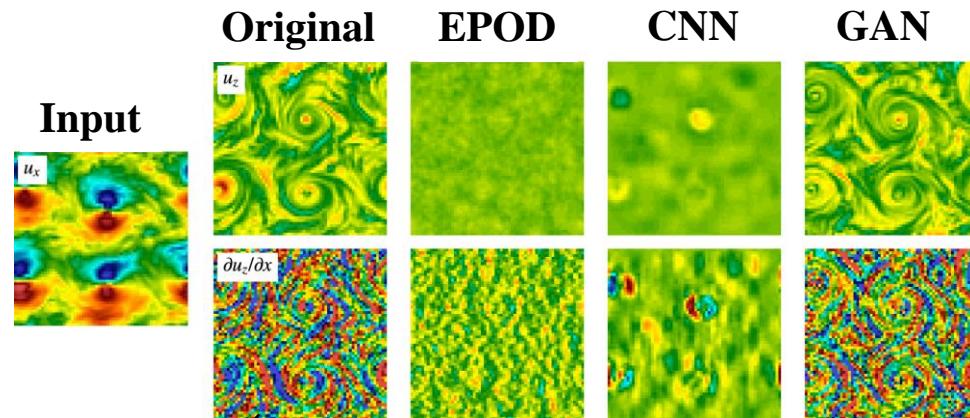
Statistical distance

$$\text{JSD}(P\|Q) = \frac{1}{2} \text{KL}(P\|M) + \frac{1}{2} \text{KL}(Q\|M),$$

$$M = \frac{1}{2}(P + Q)$$

$$\text{KL}(P\|Q) = \int_{-\infty}^{\infty} P(x) \log(P(x)/Q(x)) dx$$

Results: Inference task (II)



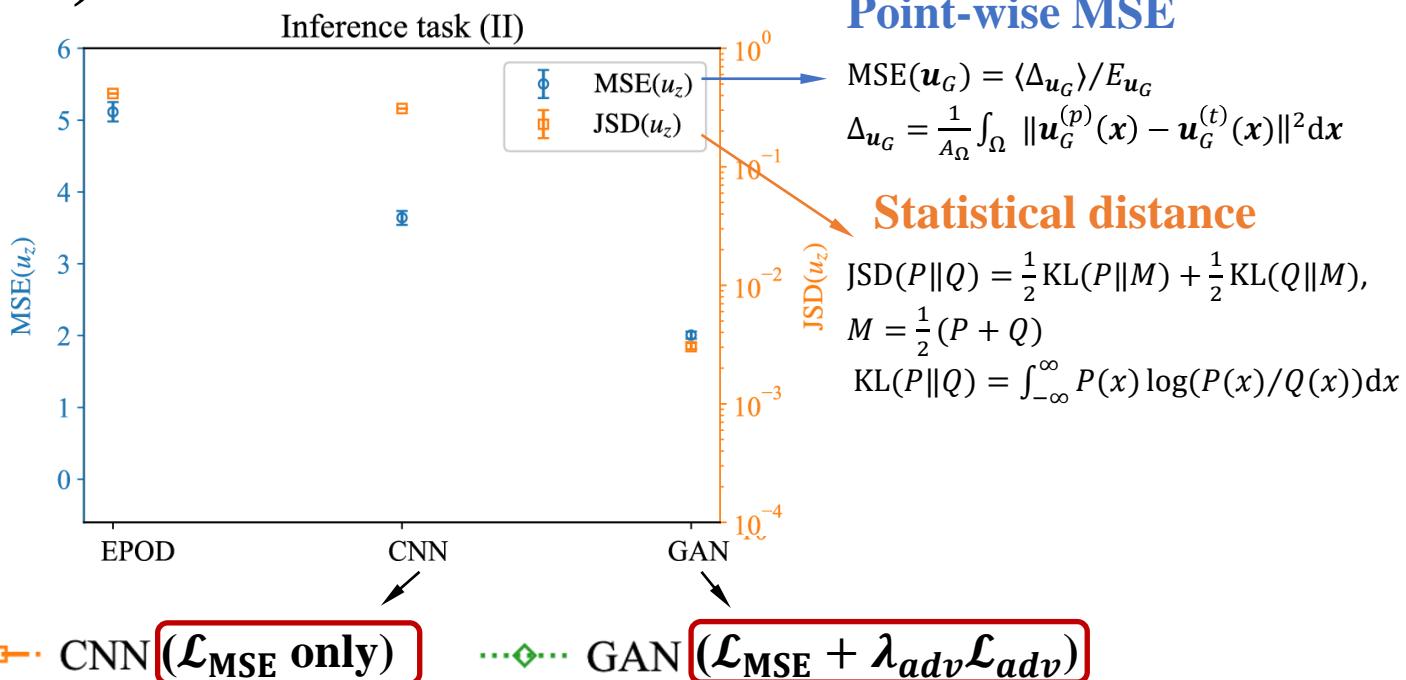
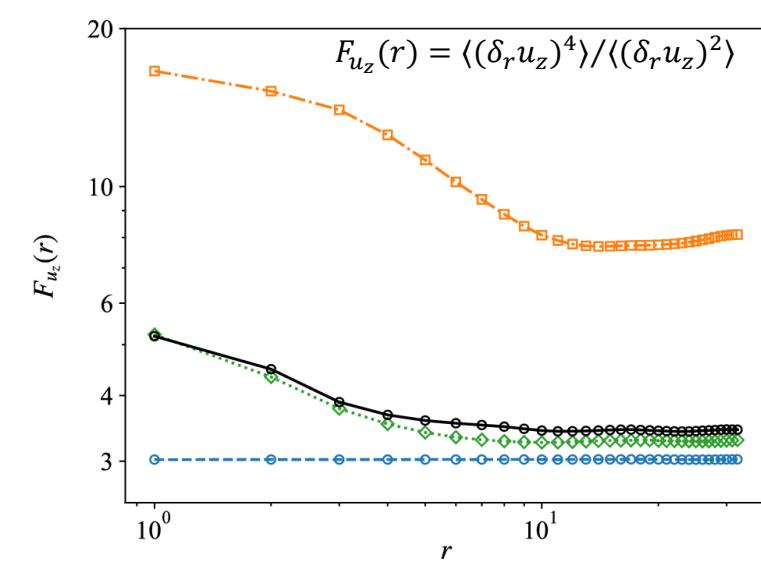
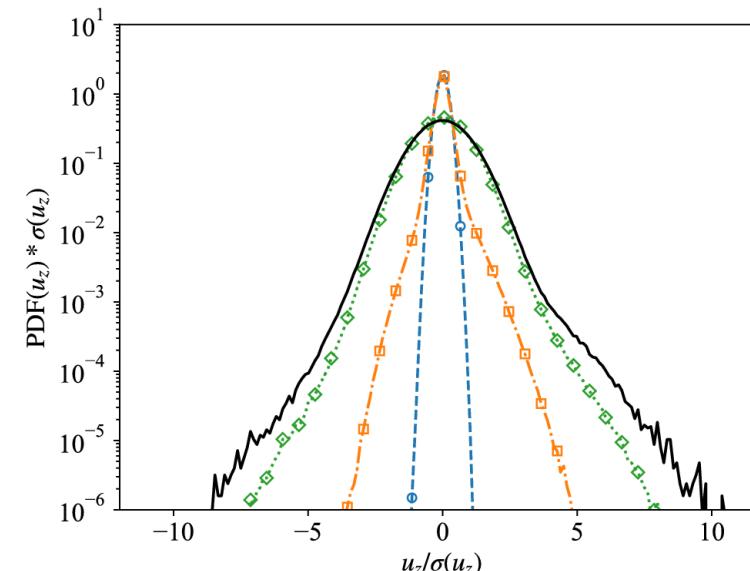
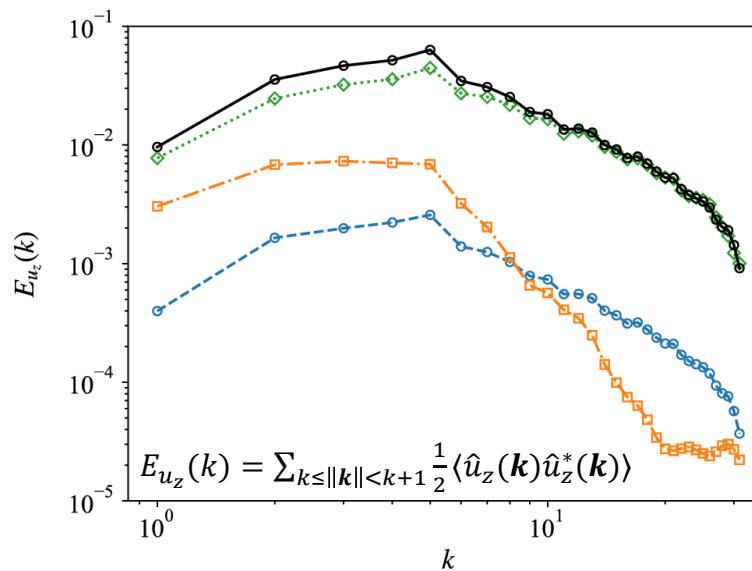
Gradient

— Original

- - o - EPOD

- - □ - CNN (\mathcal{L}_{MSE} only)

... ◆ ... GAN ($\mathcal{L}_{\text{MSE}} + \lambda_{\text{adv}} \mathcal{L}_{\text{adv}}$)



Summary

1.Purpose: Exploring practical geophysical/engineering problem of inferring one velocity component from another in 2D rotating turbulent flows.

2.Methods: Compared linear (EPOD) and nonlinear (CNN & GAN) methods using two tasks with different complexities.

3.Findings:

1. For the task where input and output components are well correlated, EPOD produced meaningful results. Improvements observed using CNN and further refined with GAN.
2. For the task where input and output components are not well correlated, EPOD failed due to low correlation between components. CNN and GAN recognized coherent structures but had limitations.

4.Conclusion: GANs optimize both instantaneous and statistical reconstruction, outperforming EPOD, which only minimizes field variance. GANs deliver more realistic results, albeit at a higher computational cost.

**Guide for users**

TURB-ROT. A LARGE DATABASE OF 3D AND 2D SNAPSHOTs FROM TURBULENT ROTATING FLOWS

A PREPRINT

L. Biferale
Dept. Physics and INFN
University of Rome Tor Vergata, Italy, and IIC-Paris, France
biferale@roma2.infn.it

F. Bonacorso
Center for Life Nano Science@La Sapienza
Istituto Italiano di Tecnologia and INFN
University of Rome Tor Vergata, Italy.
fabio.bonacorso@roma2.infn.it

M. Buzzicotti
Dept. Physics and INFN
University of Rome Tor Vergata, Italy.
michele.buzzicotti@roma2.infn.it

P. Clark Di Leoni
Department of Mechanical Engineering,
Johns Hopkins University, Baltimore, USA.
pato@jhu.edu

Search for datasets

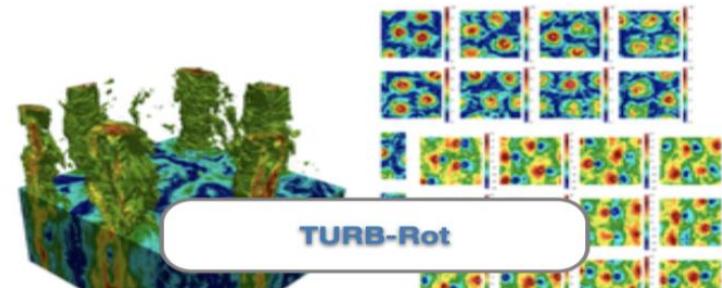


1

Datasets

TURB-Rot

A large database of 3d and 2d snapshots from turbulent rotating



2

Organizations

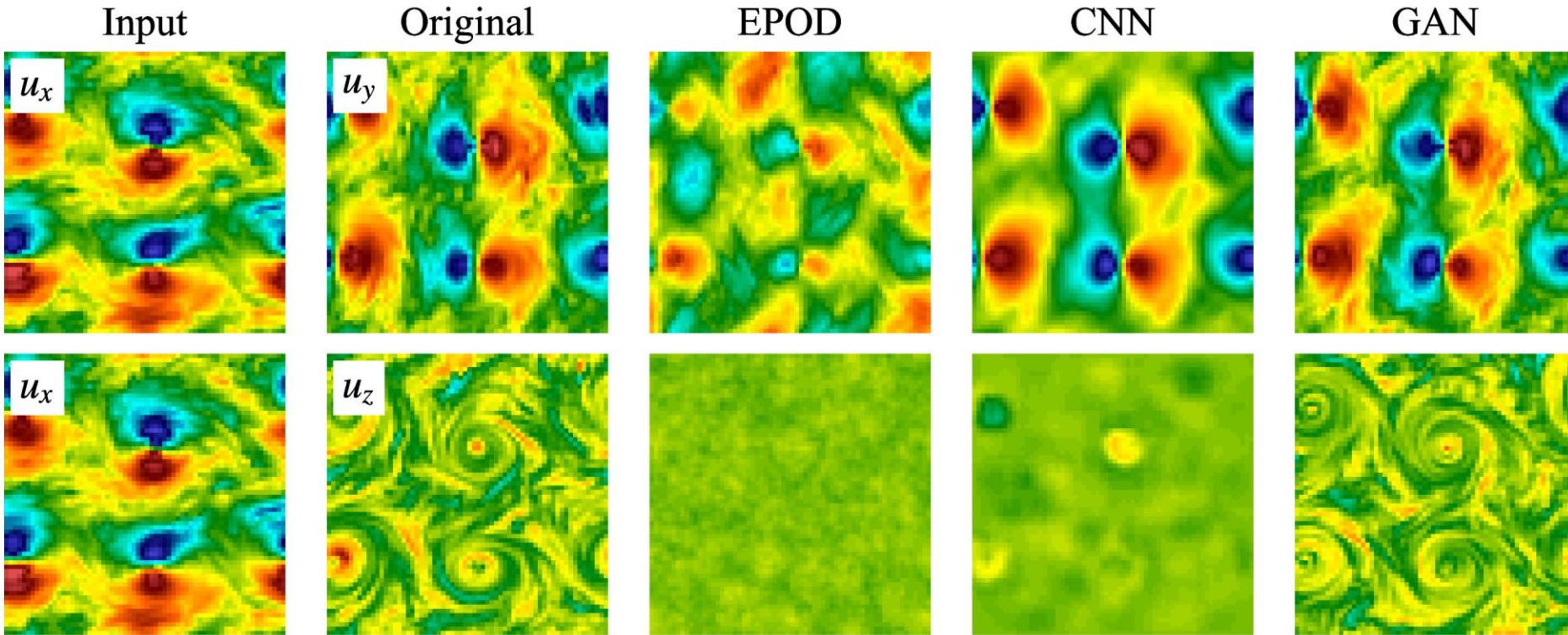
web_admin

web_admin group

1

member

Thank you! Questions?





Backup slides

Multi-scale prediction error

2D wavelet decomposition (for a $2^N \times 2^N$ grid)

$$u_y(\mathbf{x}) = \bar{u}_y + \sum_{j=0}^{N-1} u_y^{(k_j)}(\mathbf{x}), \quad (22)$$

where \bar{u}_y is the mean value and

$$u_y^{(k_j)}(\mathbf{x}) = \sum_{i_x=0}^{2^j-1} \sum_{i_y=0}^{2^j-1} \sum_{\sigma} c_{j,i_x,i_y}^{(\sigma)} \psi_{j,i_x,i_y}^{(\sigma)}(\mathbf{x}) \quad (23)$$

is the wavelet contribution at wave number $k_j = 2^j$, corresponding to the length scale $1/k_j$. Given that $\sigma \in \{x, y, d\}$, $c_{j,i_x,i_y}^{(\sigma)}$ is the wavelet coefficient and

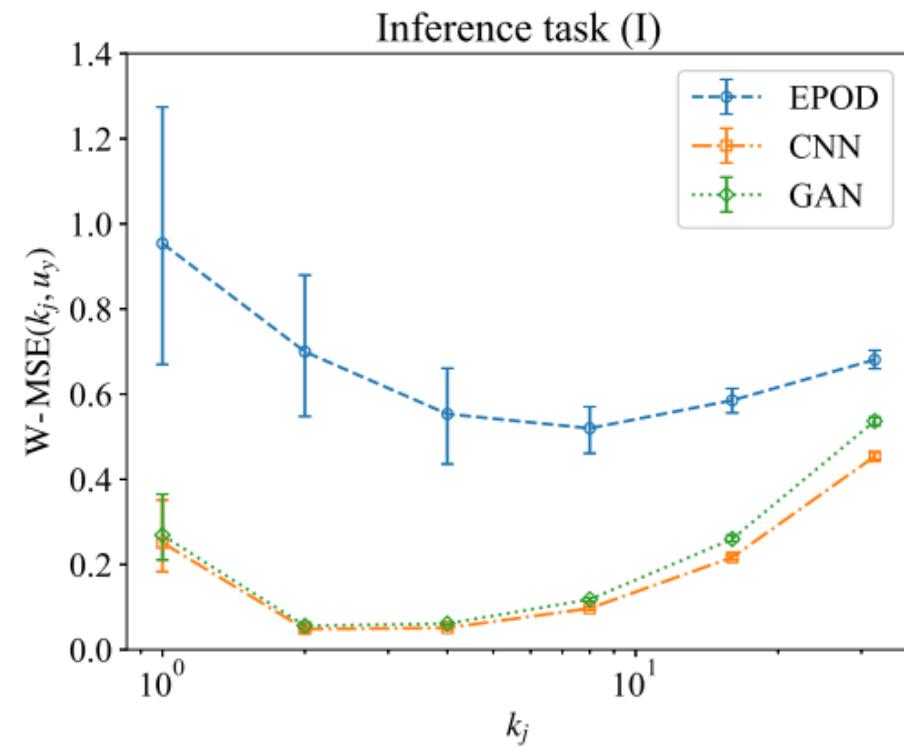
$$\begin{aligned} \psi_{j,k_x,k_y}^{(x)}(x, y) &= \psi_{j,k_x}(x)\phi_{j,k_y}(y), \\ \psi_{j,k_x,k_y}^{(y)}(x, y) &= \phi_{j,k_x}(x)\psi_{j,k_y}(y), \\ \psi_{j,k_x,k_y}^{(d)}(x, y) &= \psi_{j,k_x}(x)\psi_{j,k_y}(y), \end{aligned} \quad (24)$$

where $\phi(\cdot)$ and $\psi(\cdot)$ are the Haar scaling function and associated wavelet, respectively. To measure

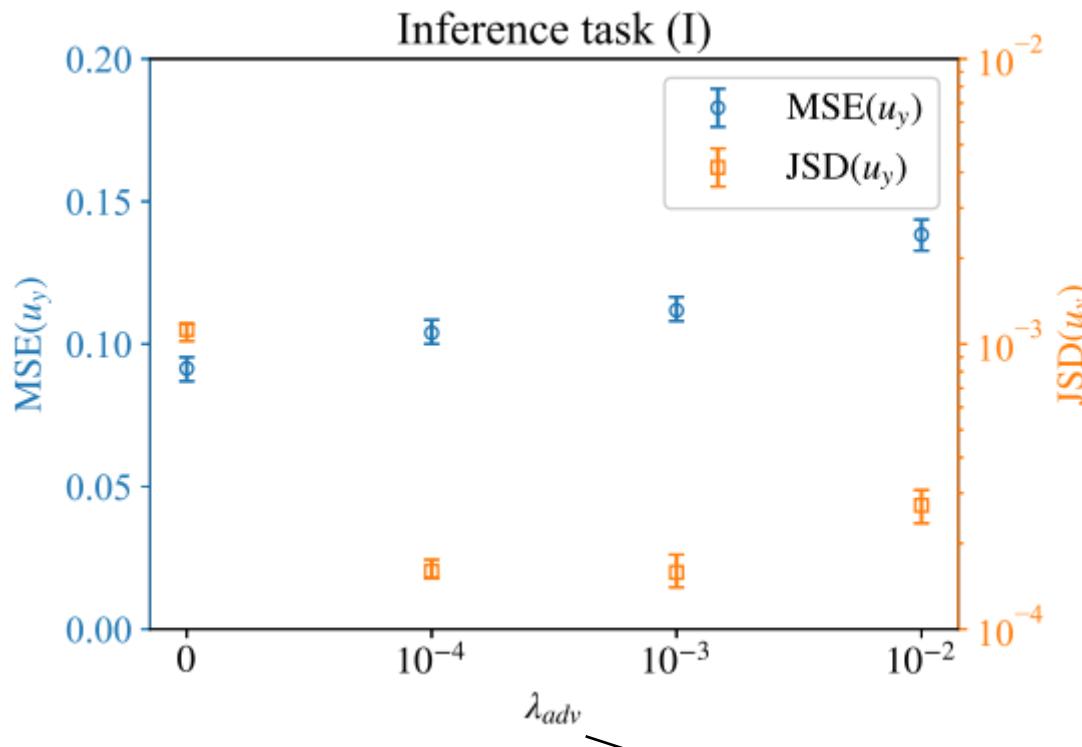
$$\begin{aligned} \text{MSE}(\mathbf{u}_G) &= \langle \Delta_{\mathbf{u}_G} \rangle / E_{\mathbf{u}_G} \\ \Delta_{\mathbf{u}_G} &= \frac{1}{A_\Omega} \int_{\Omega} \|\mathbf{u}_G^{(p)}(\mathbf{x}) - \mathbf{u}_G^{(t)}(\mathbf{x})\|^2 d\mathbf{x} \end{aligned}$$

Wavelet mean squared error (W-MSE)

$$\text{W-MSE}(k_j, u_y) = \text{MSE}(u_y^{(k_j)})$$



Dependency on adversarial ratios



$$\mathcal{L}_{GEN} = (1 - \lambda_{adv})\mathcal{L}_{MSE} + \lambda_{adv}\mathcal{L}_{adv}$$