

Entropic Lattice Boltzmann Method: An implicit Large-Eddy Simulation ?

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Motivations

Lattice Boltzmann Method:

- Adapted to a wide range of physical simulations
- Intrinsic scalability, well suited for HPC implementations
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Current direction: Study of Entropic Lattice Boltzmann Method as an implicit LBM-LES

LBGK Equation

$$f_i(\vec{x} + \vec{c}_i, t + 1) - f_i(\vec{x}, t) = -\frac{1}{\tau} [f_i(\vec{x}, t) - f_i^{eq}(\vec{x}, t)]$$

which is a relaxation of typical time τ to the local equilibrium distribution:

$$f_i^{eq}(\vec{x}, t) = w_i \rho(\vec{x}, t) \left[1 + \frac{\vec{c}_i \cdot \vec{u}(\vec{x}, t)}{c_s^2} + \frac{(\vec{c}_i \cdot \vec{u}(\vec{x}, t))^2}{2 c_s^4} - \frac{|\vec{u}(\vec{x}, t)|^2}{2 c_s^2} \right]$$

a 2^{nd} order expansion in $\frac{\vec{u}}{c_s}$ of the Maxwell-Boltzmann distribution

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- Chapman-Enskog expansion shows the relation between viscosity ν and the relaxation time τ

$$\nu = c_s^2 \left(\frac{1}{\tau} - 0.5 \right) \quad \text{where } c_s \text{ is the speed of sound in the lattice}$$

ELBM: A search for LBM stabilization

Can we use LBM to study turbulent flows?

Instabilities arise when $\tau \rightarrow 0.5$ ($\nu \rightarrow 0$) making standard LBGK irrelevant to the study of turbulent flows

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ELBM principle is to equip LBM with an in-built H-theorem

ELBM: A LBM with an in-built H-theorem

ELBM Equation

$$f_i(x + c_i, t + 1) = f_i(x, t) + \alpha\beta (f_i^{eq}(x, t) - f_i(x, t))$$

where $\beta = \frac{1}{2\tau}$. If $\alpha = 2$, the ELBM eq. becomes the LBGK eq.

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- \mathbf{f}^{eq} is defined as the maxima of a convex H-function under the constraints of mass and momentum conservation: [Karlin *et al.*, 1999]

$$H(\mathbf{f}) = \sum_0^{q-1} f_i \log \left(\frac{f_i}{\omega_i} \right), \quad \rho = \sum_i f_i^{eq}, \quad \rho \vec{u} = \sum_i \vec{c}_i f_i^{eq}$$

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- For $DdQ3^d$ lattices:

$$f_i^{eq} = \rho w_i \prod_{a=1}^d \left(2 - \sqrt{1 + 3 u_a^2} \right) \left(\frac{2 u_a + \sqrt{1 + 3 u_a^2}}{1 - u_a} \right)^{c_{i,a}}$$

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ELBM Equation

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with $0 < \beta < 1$ as we have $0.5 < \tau < +\infty$

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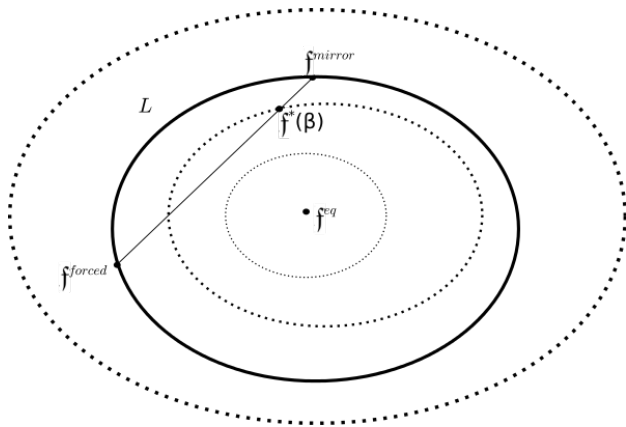
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- α is calculated at each node and each time step as the solution of the following equation:

$$H(\mathbf{f}) = H(\mathbf{f}^{\text{mirror}})$$

Calculation of α and the convexity of H insure monotonic decreases of H



Entropic step Equation

$$H(\mathbf{f}) = H(\mathbf{f} - \alpha(\mathbf{f} - \mathbf{f}^{\text{eq}}))$$

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$$\beta \rightarrow 1 \Leftrightarrow \nu \rightarrow 0\dots$$

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$$\beta \rightarrow 1 \Leftrightarrow \nu \rightarrow 0...$$

... but we need to understand if the right physics is represented

Is ELBM a LBM with an implicit LES?

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$$\nu(\alpha) = c_s^2 \left(\frac{1}{\alpha\beta} - 0.5 \right)$$

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[Malaspinas *et al.*, 2008]

- Chapman-Enskog expansion was performed for $\alpha \approx 2$ and an additional term of the form $\nu_r S_{ij}$ appeared with:

$$\nu_r = -\frac{c_s^2 \Delta t}{3(2\beta)^2} \frac{S_{\theta\kappa} S_{\kappa\gamma} S_{\gamma\theta}}{S_{\lambda\mu} S_{\lambda\mu}}$$

Very similar to a Smagorinsky subgrid scale model

KBC: Multi-relaxation time variation of ELBM

[Bosch *et al.*, 2015]

$$f_i = k_i + s_i + h_i$$
$$f_i^{mirror} = k_i + [2s_i^{eq} - s_i] + [\gamma h_i^{eq} + (1 - \gamma)h_i]$$

where k_i is the contribution of locally conserved fields

s_i are stresses

h_i are the remaining high order moments

γ is calculated to minimize the entropy of the post-collision distribution:

$$\frac{dH[\mathbf{f}']}{d\gamma} = \frac{dH[(1 - \beta)\mathbf{f} + \beta f^{mirror}]}{d\gamma} = 0$$

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Objective:

- Numerically check the existence of an implicit Sub-Grid Scale model and its impact on the physics for both 2D and 3D turbulence

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Collaborations:

- Abhineet Gupta and Federico Toschi from TU/e
- Ilya Karlin from ETH Zurich

Thank you for your attention!

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- 1: **for** each time step **do**
- 2: **for** each node **do**
- 3: Calculate density $\rho = \sum_{i=0}^{q-1} f_i$
- 4: Calculate velocity for equilibrium calculation $u^{\vec{e}q} = \frac{1}{\rho} \sum_{i=0}^{q-1} f_i \vec{c}_i + \frac{\vec{F}}{2\rho}$
- 5: Calculate the non-equilibrium part of the distribution $f_i^{\text{neq}} = f_i - f_i^{\vec{e}q}(\rho, u^{\vec{e}q})$
- 6: Apply the forcing's collision contribution to the distribution
- 7: Check the deviation $\Delta(\mathbf{f}^F, \mathbf{f}^{\text{neq}}) = \max_{0 < i < q-1} \left| \frac{f_i^{\text{neq}}}{f_i^F} \right|$
- 8: **if** $\Delta(\mathbf{f}^F, \mathbf{f}^{\text{neq}}) \leq 10^{-3}$ **then**
- 9: Set $\alpha = 2$
- 10: **else**
- 11: Calculate α_{\max} corresponding to $\min_{0 < i < q-1} \left| \frac{f_i^F}{f_i^{\text{neq}}} \right| > 0$
- 12: **if** $\alpha_{\max} < 2$ **then**
- 13: Set $\alpha = 0.9 \times \alpha_{\max}$
- 14: **else**
- 15: Use Newton-Raphson method to solve $H(\mathbf{f}^F) = H(\mathbf{f}^F - \alpha \mathbf{f}^{\text{neq}})$ with $\alpha_{\text{guess}} = 2$, $\alpha_{\min} = 1$ and previously calculated α_{\max}
- 16: **end if**
- 17: **end if**
- 18: Collide with a relaxation time of $\alpha \times \beta$
- 19: Propagate
- 20: Store density
- 21: Calculate and store hydrodynamic velocity $u^{\vec{h}dro} = \frac{1}{\rho} \sum_{i=0}^{q-1} f_i \vec{c}_i + \frac{\vec{F}}{2\rho}$
- 22: **end for**
- 23: **end for**